APM Tutorial: Improving load following capabilities of natural gas and coal-fired boilers



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Discussion Objectives

- Cogeneration opportunities
 - > UT Austin example
 - > Challenges: Boiler fatigue
- Model forms
 - > Empirical MPC
 - System identification
 - First Principles
 - Model development
- Comparisons of PID vs Non-linear MPC
- Future Work



Cogeneration



E‰onMobil

Typical Industrial Cogeneration System



3000 large onshore wind turbines

\approx half of **Belgium's annual residential electricity** demand

Source: Meidel, R.W. (2012) Cogeneration, Challenges and Opportunities: Meeting Cogeneration TArgets in the Marketplace.

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Diagrams Courtesy Kody Powell, UT Austin

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Boiler Fatigue



Load Cycling



Photos & Diagram Courtesy NREL http://www.nrel.gov/docs/fy11osti/51579.pdf

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Control System Developments

- > Typically based on:
 - > Operator Knowledge
 - Safe
 - Meet Requirements
 - > Successful
 - > Perceived Limitations
 - > Challenge assumptions
 - Optimize everything





Special Controls



- Most processes have unique operating conditions and requirements
- Ex: Boiler for steam/energy production
 - Load change at specified rate
 - > Wear and tear
 - > Emissions



Empirical Models



- Can help in identifying cause and effect relationships within the boiler's MVs and CVs
- Information from empirical models can help develop better first principles models



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Model Identification





Inputs: gas flow, supply water flow

Outputs: (1) drum level (2) steam temp (3) steam pressure (4) drum pressure (5) steam flow

Confidence Intervals





Step Response





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Model



- Model Source
 - Operational knowledge from
 - > Literature values
 - Heat transfer equations
 - Material and energy balances
- Model Form
 - Differential and Algebraic Equations (DAEs)
 - Combined Empirical and First Principles forms



Nonlinear Model Predictive Control

- > Trajectory tracking
- Other constraints
 can be specified
 - Rate of Temperature Change
 - Emissions, Costs,
 Process unit life, etc.





Nonlinear Model Predictive Control

- Effective over entire range of interest
 - Load Following
 - Large Disturbances
 - Steady State
 - Transient
- Large-scale problems
 - > Sparse NLP solvers
 - Simultaneous
 Solution Approach



 $\min_{u} J(x, u, \Delta u)$ s.t. 0 = f(x, x, u) 0 = g(x, u) 0 < h(x, u)

PID Controller



> SIMPLE

- > Easy to Use
- > Effective for:
 - Steady state
 - Small Disturbances
- > Ineffective
 - Load Cycling
 - Frequently Saturated
 - > Violated Rate Constraints

PID Start-Up









NLC Start Up











Comparison of Set Point Changes

PID Control



Nonlinear Control



Model-Based Controller



- Challenges restrictions by driving to actual process constraints
 - > Optimized load changes
 - i.e. Faster/slower, boiler life
- > Explicitly Targeted Constraints

Future Work



- > Empirical MPC
 - Model identification
 - cause and effect relationships within the boilers MVs and CVs
- Develop thermal stress model of thermal sensitive areas (super heated steam headers)
- Forecasting:
 - > Energy availability
 - > Time of day pricing
 - > Peak power demands
- > Energy storage
 - > Optimize design and operation
 - Meet peak demand with lower base-load

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